Amendments to the Claims:

This listing of claims will replace all prior versions, and listings, of claims in the

application:

Listing of Claims:

1. (currently amended) A magnetoresistive speed sensor a comprising a permanent

magnet and a magnetic field detecting sensor for detecting the speed of an object rotating

about an x-axis, wherein the magnetoresistive speed sensor has a measuring direction,

characterized in that the measuring direction is aligned parallel with the x-direction, and

two magnetic field detecting sensors are disposed on a y-axis essentially in the direction

of the movement of the nearest portion of the object at a distance from one another and

perpendicular to the measuring direction, wherein each of the two magnetic field

detecting sensors generates an output signal.

2. (previously presented) A magnetoresistive speed sensor as claimed in claim 1,

characterized in that the magnetic field detecting sensors are disposed symmetrically in

relation to the x-axis on the y-axis.

3. (previously presented) A magnetoresistive speed sensor as claimed in claim 1,

characterized in that each of the magnetic field detecting sensors is a Wheatstone bridge.

4. (previously presented) A magnetoresistive speed sensor as claimed in claim 1,

characterized in that each of the magnetic field detecting sensors is a half bridge.

5. (previously presented) A magnetoresistive speed sensor as claimed in claim 1,

characterized in that the permanent magnet has a magnetic field component in the x-

direction.

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Amendment and Response to Office Action

- 6. (previously presented) A use of a magnetoresistive speed sensor as claimed in claim 1, in automotive engineering.
- 7. (previously presented) The use of a magnetoresistive speed sensor as recited in claim 6, wherein the automotive engineering includes at least one of the following: crankshaft speed monitoring, camshaft speed monitoring, or monitoring of an anti-lock braking (ABS) system.
- 8. (currently amended) A magnetoresistive speed sensor comprising a permanent magnet and a magnetic field detecting sensor for detecting the speed of an object rotating about an x-axis, wherein

the magnetoresistive speed sensor has a measuring direction, characterized in that the measuring direction is aligned parallel with the x-direction, and two magnetic field detecting sensors are disposed at a distance from one another symmetrically in relation to the x-axis on the y-axis and perpendicular to the measuring direction, wherein each of the two magnetic field detecting sensors generates an output signal.

- 9. (previously presented) The magnetoresistive speed sensor as recited in claim 8, wherein each of the magnetic field detecting sensors is a Wheatstone bridge.
- 10. (previously presented) The magnetoresistive speed sensor as recited in claim 8 wherein each of the magnetic field detecting sensors is a half bridge.
- 11. (previously presented) The magnetoresistive speed as recited in claim 8, wherein the permanent magnet has a magnetic field component in the x-direction.
- 12. (previously presented) The magnetoresistive speed as recited in claim 9, wherein the permanent magnet has a magnetic field component in the x-direction.
- 13. (previously presented) The magnetoresistive speed as recited in claim 10, wherein the permanent magnet has a magnetic field component in the x-direction.

- 14. (currently amended) A magnetoresistive speed sensor comprising, a permanent magnet having a magnetic field component in the x-direction; and a magnetic field detecting sensor for detecting the speed of an object rotating about an x-axis, the magnetic field detecting sensor being a Wheatstone bridge, wherein the magnetoresistive speed sensor has a measuring direction, characterized in that the measuring direction is aligned parallel with the x-direction, and two magnetic field detecting sensors are disposed at a distance from one another symmetrically in relation to the x-axis on the y-axis and perpendicular to the measuring direction, wherein each of the two magnetic field detecting sensors generates an output signal.
- 15. (new) The magnetoresistive speed sensor as claimed in claim 1, wherein the output signals from the two magnetic field detecting sensors comprise a first output signal from a first magnetic field detecting sensor and a second output signal from a second magnetic field detecting signal, and wherein the magnetoresistive speed sensor is further configured to calculate a differential signal of the first and second magnetic field detecting sensors based on the first and second output signals.
- 16. (new) The magnetoresistive speed sensor as claimed in claim 8, wherein the output signals from the two magnetic field detecting sensors comprise a first output signal from a first magnetic field detecting sensor and a second output signal from a second magnetic field detecting signal, and wherein the magnetoresistive speed sensor is further configured to calculate a differential signal of the first and second magnetic field detecting sensors based on the first and second output signals.
- 17. (new) The magnetoresistive speed sensor as claimed in claim 14, wherein the output signals from the two magnetic field detecting sensors comprise a first output signal from a first magnetic field detecting sensor and a second output signal from a second magnetic field detecting signal, and wherein the magnetoresistive speed sensor is further configured to calculate a differential signal of the first and second magnetic field detecting sensors based on the first and second output signals.